Structured SVMs and Conditional Random Fields for Semantic Segmentation

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SSVM

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Motivation

Histopathological Image Analysis with Deep Learning Patch Level Classification Challenges

Classification of Structured Data

Structured Input and Output Semantic Segmentation Naive Approach Binary SVM Review Multi-class SVM Review Structured Support Vecto Machines

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Semantic Segmentation Using CRFs and CNN Features

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Histopathological Image Analysis with Deep Learning

Histopathology is the examination of tissues from the body under a microscope to spot the signs and characteristics of disease.

Currently in our research project we are trying to classify patches of breast tissues into cancerous and normal classes.

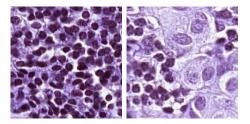


Figure: The left image is a sample of normal patch and the right is a sample of abnormal.

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Patch Level Classification Challenges

Existence of darker and smaller normal cells in cancerous regions is possible. Thus, the patch-level classifier (Tuned VGG16) sometimes make False Normal decisions.

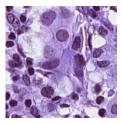


Figure: Existence of normal cells (features) in the abnormal patches

Solution: Take spatial relations between patches into account. (Neighbors)

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Structured Input and Output

Two Types of data:

- Flat Data: Numbers
- Structured Data: Sequences

Input and output of the ML problems can be either flat or structured.

- Simple Image Classification, Stock Market Index Prediction (Structured – Flat)
- Labeling Image Segments, Part of Speech Tagging (Structured – Structured)

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Semantic Segmentation

Linking each Pixel/Superpixel to a label. Structured matrix of Superpixels to Structured matrix of labels (with the same size)



Figure: Real examples of Semantic Segmentation

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A Naive Approach is to create a specific class for each combination of possible labeling and then use a desired classifier.

Problem?

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A Naive Approach is to create a specific class for each combination of possible labeling and then use a multi-class classifier.

Problem? Exponential classes and parameters.

Solution. Use Structured Support Vector Machine.

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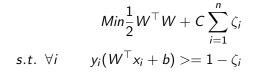
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Binary SVM Review



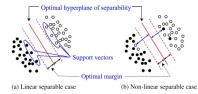


Figure: A simple example of Binary SVM

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Multi-class SVM Review

One approach in Multi-class classification using SVM is the "one v.s. all" method.

Prediction: $argmax_m W_m^{\top} x + b_m$ Training Formula:

$$Min\frac{1}{2}\sum_{m=1}^{K}W_{m}^{\top}W_{m}+C\sum_{i=1}^{n}\sum_{m\neq y_{i}}\zeta_{i}^{m}$$

s.t. $\forall i \forall m \neq y_{i}$ $W_{y_{i}}^{\top}x_{i}+b_{y_{i}} >= W_{m}^{\top}x_{i}+b_{m}+2-\zeta_{i}$

where y_i is the true class for x_i and m is any other class. Intuition: for all data points, the inner product of correct label weight vector with input, should be bigger than the inner product of any other weight vector with the input.

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Structured Support Vector Machines

Multi-class SVM for Structured data is not good:

- Exponential parameters, constraints
- No efficient prediction algorithm
- No efficient training algorithm

We need to avoid searching through all possible outputs (all possible labelings in our case).

Structured SVM helps us doing that.

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Structured Support Vector Machines

In SSVM we map all combination of input and output instances to a space of fixed dimensionality, called the feature map. Then instead of searching in the output space, we search in this feature space. Components of SSVM:

- Feature / Compatibility Function : $\psi(x, y)$
- Weight Vector: W
- Discrimination / Scoring Function: $W^{\top}\psi(x, y)$
- Loss Function (could be optional): $\Delta(y, y_i)$

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Structured Support Vector Machines

The form of the optimization equation is:

$$argmin_{W,\zeta} \qquad \frac{1}{2}W^{\top}W + C\sum_{i=1}^{n}\zeta_{i}$$

s.t. $\forall i \ \forall y \neq y_{i} \qquad W^{\top}\psi(x_{i}, y_{i}) - W^{\top}\psi(x_{i}, y) > = \Delta(y_{i}, y) - \zeta_{i}$

$$\forall i \zeta_i >= 0$$

Margin Rescaling: Since the margin is not constant.

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Feature Map / Compatibility Function

Intuition: Somehow represents the compatibility between each input x and output y.

Typically is a combination of two specific function:

- Unary Potential/Compatibility Function: compatibility between local fragments of input and output.
- Binary Portential/Compatibility Function: compatibility between the local labels (output).

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Scores the compatibility of a given input x and output y.

$W^{\top}\psi(x,y)$

We should define a good feature space under which we can tune W such that the score for correct labels becomes higher than the score for incorrect ones.

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Gives us a measure of how different is an incorrect output from a correct output.

 $\Delta(y_i, y)$

Can simply be the euclidean distance between the two given outputs.

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Prediction Using SSVMs

$$\hat{y} = \operatorname{argmax}_{y} W^{\top} \psi(x_i, y)$$

Intuition: in some sense we are finding an output that is most compatible with our input.

We need to have a good approach on maximizing the score by finding a good y. Iterating over all possible outputs is a waste of time. Having this algorithm highly depends on how we define the feature space and also on the domain itself.

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Training SSVMs Using Cutting Plains Alg.

The form of the optimization equation is:

$$\frac{1}{2}W^{\top}W + C\sum_{i=1}^{n}\zeta_{i}$$

s.t. $\forall i \forall y \neq y_{i}$ $W^{\top}\psi(x_{i}, y_{i}) - W^{\top}\psi(x_{i}, y) > = \Delta(y_{i}, y) - \zeta_{i}$

$$\forall i \zeta_i >= 0$$

Problem?

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Training SSVMs Using Cutting Plains Alg. The form of the optimization equation is:

$$\frac{1}{2}W^{\top}W + C\sum_{i=1}^{n}\zeta_{i}$$

s.t. $\forall i \forall y \neq y_{i}$ $W^{\top}\psi(x_{i}, y_{i}) - W^{\top}\psi(x_{i}, y) > =$
 $\Delta(y_{i}, y) - \zeta_{i}$

$$\forall i \zeta_i >= 0$$

Problem? We have exponential number of constraints. It is inefficient to use all of them (if not impossible).

Solution: Start with empty set of constraints and iteratively add more constraints. Add the most violating constraint for each input data (Cutting Plains Algorithm). Another method is Gradient Descent.

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Training SSVMs Using Cutting Plains Alg.

One algorithm is called Cutting Plains:

CUTTING_PLAINS() repeat K_old = K For i = 1 ... n $\hat{y} = \operatorname{argmax}_{y \neq y_i} - (W^\top \psi(x_i, y_i) - W^\top \psi(x_i, y)) + \Delta(y_i, y)$ If $W^\top \psi(x_i, y_i) - W^\top \psi(x_i, \hat{y}) < \Delta(y_i, \hat{y}) - \zeta_i$ Then $K = K \cup \{W^\top \psi(x_i, y_i) - W^\top \psi(x_i, \hat{y}) >= \Delta(y_i, \hat{y}) - \zeta_i\}$ $\{W, \zeta\} = \operatorname{argmin}_{W, \zeta} \frac{1}{2} W^\top W + C \sum_{i=1}^n \zeta_i$ s.t. K End If End For Until K = K_old

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Training SSVMs Using Cutting Plains Alg.

Sometimes coming up with a good algorithm for finding \hat{y} in

$$\hat{y} = \operatorname{argmax}_{y \neq y_i} - (W^{\top}\psi(x_i, y_i) - W^{\top}\psi(x_i, y)) + \Delta(y_i, y)$$

is difficult. In some domains, there might be a good algorithm (parsing sentences).

One approach is to not find the wrongest solution but to find a wrong solution. People have used MCMC around the correct solution to find a wrong solution.

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CRF Review

Provides the following model:

$$P(y|x) = \frac{1}{Z}exp(f(x,y))$$

Where f is a feature function and Z is the normalization term. The feature function gives an score to the labeling y for a given x. Feature function can be handcrafted or can be learned through a process.

Conditional Random Fields take the **local relationship** between the fragments of input and output into consideration.

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They first group the pixels of their input image into superpixels. Then they form the conditional random field as:

$$P(y|x;w) = \frac{1}{Z}exp(-E(y,x;w))$$

where,

$$E(y, x; w) = \sum_{p \in N} \Psi^{(1)}(y^p, x; w) + \sum_{p,q \in S} \Psi^{(2)}(y^p, y^q, x; w)$$

N is the list of all superpixels, S is the list of all neighboring superpixels, y is a labeling, Ψ functions are the potential functions and (p,q) are a pair of neighboring superpixels. When the input and output are less compatible, energy is high.

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$$P(y|x;w) = \frac{1}{Z}exp(-E(y,x;w))$$

$$E(y, x; w) = \sum_{p \in N} \Psi^{(1)}(y^p, x; w) + \sum_{p,q \in S} \Psi^{(2)}(y^p, y^q, x; w)$$

Finding a best labeling with CRF and MAP: (1) learn model parameters, (2) infer a most likely label using a method. Thus segmentation problem is now reduced to minimizing the Energy function using the learned parameters as:

$$\hat{y} = \operatorname{argmin}_{y \in Y} E(y, x; w)$$

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Learning the Weights and Predict Using SSVM

We can learn the parameters of our CRF by creating and training the following Structured SVM:

$$\begin{aligned} \min_{w,\zeta} \quad \frac{1}{2} w^{\top} w + C \sum_{i=1}^{n} \zeta_i \\ s.t. \ \forall i \ \forall y \neq y_i \in Y \qquad E(y, x_i; w) - E(y_i, x_i; w) > = \\ \Delta(y_i, y) - \zeta_i \end{aligned}$$

$$\forall i \zeta_i >= 0$$

Intuition: Energy of GT label lower than the energy of any incorrect label by at least a margin determined by the loss function. Loss function used is weighted Hamming loss. (fraction of wrong labels to the total number of labels)

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They defined their potential functions as linear functions in the parameter w. Thus we will have:

$$\Psi^{(1)}(y^p, x; w) = \langle w^{(1)}, \psi^{(1)}(y^p, x) \rangle$$

$$\Psi^{(2)}(y^{p},y^{q},x;w) = \langle w^{(2)},\psi^{(2)}(y^{p},y^{q},x)
angle$$

where <,> indicates the inner product and the vector w is made by stacking the two vectors $w^{(1)}$ and $w^{(2)}$.

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The Potential Functions

Unary potential function:

$$\psi^{(1)}(y^p, x) = [I(y^p = 1)x^{p^{\top}} \dots I(y^p = K)x^{p^{\top}}]$$

where, I(.) is the indicator function, $x^{p^{\top}}$ is the deep learning feature vector for superpixel p, K is the number of classes.

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The Potential Functions

Binary potential function:

$$\psi^{(2)}(y^{p}, y^{q}, x) = \psi_{1}^{(2)}(y^{p}, y^{q}, x) + \psi_{2}^{(2)}(y^{p}, y^{q}, x) + \psi_{3}^{(2)}(y^{p}, y^{q}, x) + \psi_{4}^{(2)}(y^{p}, y^{q}, x)$$

Where,

$$\psi_{i}^{(2)}(y^{p}, y^{q}, x) = L_{pq}.I(y^{p} \neq y^{q}).g_{i}(y^{p}, y^{q})$$

where L_{pq} is either the shared boundary length between the two superpixels or inversed color difference and g_i responds to the inverse of the frequency of co-occurrences of the two labels in four spatially related neighboring. (Next Slide)

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$$g_i(y^p, y^q) = \frac{1}{f_{co-occurance}^i(y^p, y^q)}$$

$$f^{i}_{co-occurance}(y^{p},y^{q}) = rac{N^{i}_{pq}}{N_{pq}}$$

where N_{pq} is the number of training images in which y^p and y^q coexist, N_{pq}^i are the number of training images in which y^p and y^q appear in four spatially related neighborings.

They have a hyper-parameter that determines the effect of co-occurrence function g on the binary potential.

SSVM

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Results

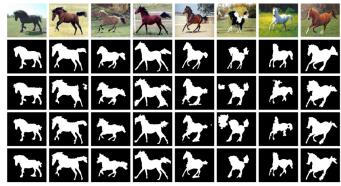


Fig. 2. Segmentation examples on Weizmann horse. 1st row: test images; 2nd row; ground truth; 3rd row: segmentation results produced by SSVM based CRF learning with bag-of-words feature; 4th row: segmentation results produced by SSVM based CRF learning with unsupervised feature learning; 5th row: segmentation results produced by SSVM based CRF learning with the function of the learning with a set of the learning with the set of the set of the set of the learning with the set of the set o

Figure: Effect of choosing different features for $x^{p^{\top}}$

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Results

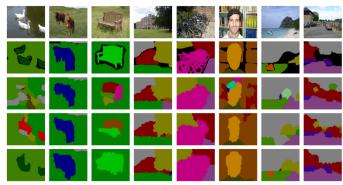


Fig. 4. Segmentation examples on MSRC. 1st row: test images; 2nd row; ground truth; 3rd row: segmentation results produced by SSVM based CRF learning with bag-ofwords feature; 4th row: segmentation results produced by SSVM based CRF learning with unsupervised feature learning; 5th row: segmentation results produced by our method with co-ocurrence pairwise potentials.

Figure: Effect of choosing different features for $x^{p^{\top}}$

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Average Per-Category pixel accuracy on MSRC-21 and Stanford Background datasets are 90.5% and 76.9%.

pixel accuracy : $\frac{TP+TN}{TP+TN+FP+FN}$

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Results

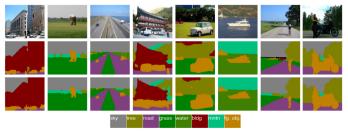


Fig. 5. Segmentation examples on the Stanford Background dataset. 1st row: test images; 2nd row: ground truth; 3rd row: segmentation results produced by our method with co-occurrence pairwise potentials.

Figure: Segmentation Example on Stanford Background dataset

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