

# Layer-wise Relevance Propagation in Neural Networks to have more interpretable Machine Learning models

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LRP

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## Motivation

- Having More interpretable Neural Networks
- Deep Learning Shortcomings
- Papers and Demo

## Introduction

- Terminology and Notations
- Relevance Properties
- Examples of Relevance
- Taylor Decomposition as Relevance

## Layer-wise Relevance Propagation

- Local Layer-wise Relevance
- Notes on Relevance Rules
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- LRP Rules
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  - LRP-Epsilon
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  - LRP Rules Comparison
- Which Rule to use for each layer
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# Having More interpretable Neural Networks

- ▶ Interpretable Machine Learning (ML) Theme in our Colloquium
- ▶ Medical Applications of ML, specially Medical Image Analysis
- ▶ Deep Learning (DL) for analyzing histopathological Slides

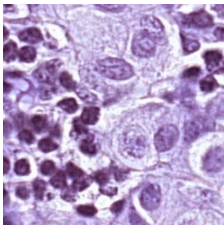


Figure: A sampled window inside the cancerous region of a Slide

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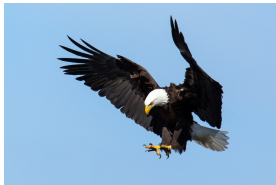
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- ▶ Paying Attention to irrelevant and spurious features



- ▶ Feature Selection not useful.

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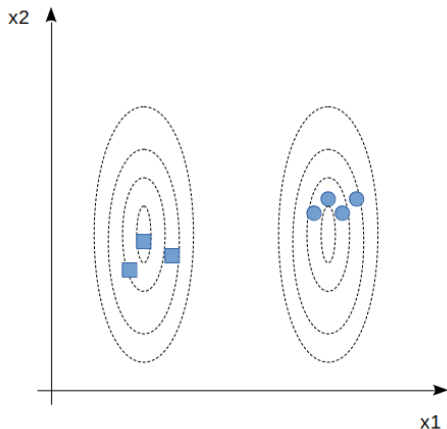
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- ▶ Paying Attention to irrelevant and spurious features  
Simple example:



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# Deep Learning Shortcomings

- ▶ Deep Neural Networks' Challenges Medical Sciences
  - ▶ Fix this problem
  - ▶ Explain the predictions of the Models

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- ▶ Layer-Wise Relevance Propagation: An Overview (Explainable AI: Interpreting, Explaining and Visualizing Deep Learning Chapter 10)
- ▶ Explaining nonlinear classification decisions with deep Taylor decomposition (Elsevier Pattern Recognition)

Demo: [Link](#)

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Why the neural network is making a particular decision.

- ▶ Assess and Validate the prediction and the reason behind it with another inexpensive method.
- ▶ Given the final output of a class (softmax), where in the input the network is attending.
- ▶ Which parts of the input affect the prediction (positively and negatively).

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# Terminology and Notations

Note: we focus on images and CNNs in this talk but LRP can be applied to all other forms of data and networks and models.

- ▶ Input Image:  $x \in \mathbb{R}^d = \{x_p\}$  ,  $p \in \{1, 2, \dots, d\}$
- ▶ Prediction:  $f(x) : \mathbb{R}^d \rightarrow \mathbb{R}^+$  quantifies the presence of an object in the input.
  - ▶ Zero: absence of the object
  - ▶ Other values: degree of certainty
- ▶ Relevance:  $R(x) : \mathbb{R}^d \rightarrow \mathbb{R}^{+d}$  Heatmap with the same size as the input

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# Relevance Properties

1. Conservation:  $\forall x : f(x) = \sum_p R(x)_p$
2. Being Positive:  $\forall x, p : R(x)_p \geq 0$
3. Consistent: if properties 1 and 2 hold. if  $f(x) = 0 \Rightarrow \forall p : R(x)_p = 0$

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# Examples of Relevance

1. Put all relevance to one pixel
2. Divide the relevance equally between all input pixels
3. Natural Decomposition: if the function  $f$  has some sort of natural decomposition between the input pixels.

$$f(x) = \sum_p f_p(x_p) \Rightarrow \forall p : R(x)_p = f_p(x_p)$$

4. Taylor Decomposition around a reference point.

$$f(x) = f(\tilde{x}) + \left(\frac{\partial f}{\partial x} \Big|_{x = \tilde{x}}\right)^T (x - \tilde{x}) + \epsilon$$

$$f(x) = 0 + \sum_p \frac{\partial f}{\partial x_p} \Big|_{x = \tilde{x}} (x_p - \tilde{x}_p) + \epsilon$$

$$\forall p : R(x)_p = \frac{\partial f}{\partial x_p} \Big|_{x = \tilde{x}} (x_p - \tilde{x}_p)$$

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# Taylor Decomposition as Relevance

Taylor Decomposition around a reference point.

$$f(x) = f(\tilde{x}) + \left(\frac{\partial f}{\partial x}\bigg|_{x=\tilde{x}}\right)^\top (x - \tilde{x}) + \epsilon$$

$$f(x) = 0 + \sum_p \frac{\partial f}{\partial x_p}\bigg|_{x=\tilde{x}} \times (x_p - \tilde{x}_p) + \epsilon$$

$$\forall p : R(x)_p = \frac{\partial f}{\partial x_p}\bigg|_{x=\tilde{x}} \times (x_p - \tilde{x}_p)$$

- ▶ Relevance: The amount of change in  $f$  when we substitute the reference point with our input image.
- ▶ Not good in practice:
  - ▶ Shattered (Noisy) Gradients
  - ▶ Adversarial Examples: small perturbation in  $x$ , changes  $f$  a lot.

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# Layer-wise Relevance Propagation

- ▶ Propagating prediction  $f(x)$  backwards through the network to the input layer using local propagation rules.
- ▶ Highlight relevant and irrelevant regions over the input to the value of the prediction for a given class.
- ▶ Conservation property holds, both locally and globally.

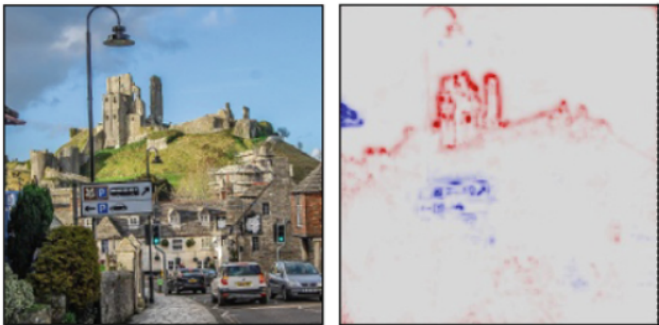


Figure: Relevance of each pixels for the class 'Castle'

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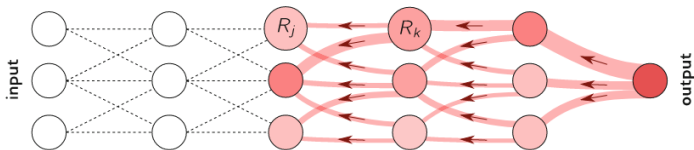


Figure: LRP in a glance

- ▶ Propagating relevance from neurons  $k$  at layer  $l_2$  onto neuron  $j$  of the lower layer  $l_1$  with the following rule:

$$R_j = \sum_{k \in A} \frac{z_{jk}}{\sum_{j \in B_k} z_{jk}} R_k$$

Where ,

$$A = \{n | n \in l_2, n \in N(j)\}$$

$$\forall k \in A, B_k = \{m | m \in l_1, k \in N(m)\}$$

Note: be aware of the notation change!

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$$\forall k \in A, B_k = \{m | m \in l_1, k \in N(m)\}$$

- ▶  $z_{jk}$  is the extent that neuron  $j$  has contributed to make neuron  $k$  relevant (i.e. activation of  $j$  times weight).
- ▶  $\frac{z_{jk}}{\sum_{j \in B_k} z_{jk}}$  resembles the proportion of relevance propagated from neuron  $k$  to neuron  $j$ . (Conservation property)

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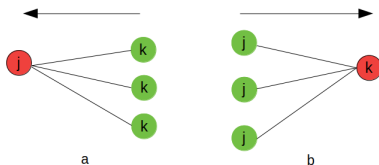


# Notes on Relevance Rules

- ▶ Activations should be ReLu.
- ▶ Substitute  $z_{jk}$  with activation times weights:

$$R_j = \sum_{k \in A} \frac{a_j w_{jk}}{\sum_{j \in B_k} a_j w_{jk}} R_k$$

- ▶ The Rule:



**Figure:** Propagation Rule. 'a' corresponds to the outer sum where we want to calculate the total amount of relevance going to the neuron  $j$ . 'b' corresponds to the inner sum in the denominator where we calculate the total amount of signal going to neuron  $k$  in order to calculate the proportion by which  $j$  has contribute to make  $k$  relevant

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# General Algorithm

1. **Forward Pass:** Start by feeding the image into the network and running the forward pass. Keep the activation values at each neuron.
2. **Initialize Relevance:** At the final layer (output), choose a class  $c$  (may not be the predicted class) and set the value of the relevance of that neuron  $R_c$  to its activation  $a_c$  \* (softmax or sigmoid). Set the rest of the output neurons relevance to zero.
3. **Apply Relevance Rules:** propagate the relevance using the relevance rule(s) backward until you reach to input layer.
4. **Visualize:** by generating a heatmap over the relevance of input nodes, visualize the results.

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The general form of the LRP Rule:

$$R_j = \sum_k \frac{a_j \rho(w_{jk})}{\sum_j a_j \rho(w_{jk})} R_k$$

- ▶ LRP-0
- ▶ LRP- $\epsilon$
- ▶ LRP- $\gamma$

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The basic case which we saw earlier.  $\rho(\cdot)$  is identity function here.

$$R_j = \sum_k \frac{a_j w_{jk}}{\sum_j a_j w_{jk}} R_k$$

- ▶ We can show that this is simply Gradient  $\times$  Input (the form we have in backprop algorithm). Thus it is unstable.

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First enhancement of LRP-0.  $\rho(\cdot)$  here is again identity function. But a small positive term is added to the denominator to absorb weak or contradictory contribution.

$$R_j = \sum_k \frac{a_j w_{jk}}{\epsilon + \sum_j a_j w_{jk}} R_k$$

- ▶ Sparser and less noisy relevance.

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# LRP-Gamma

Another enhancement of LRP-0.  $\rho(\cdot)$  \* here is the following function:

$$\rho(x) = (1 + \gamma) \frac{\text{sign}(x)+1}{2} x$$

If we apply this function to the LRP-0, we will get:

$$R_j = \sum_k \frac{a_j(w_{jk} + \gamma w_{jk}^+)}{\epsilon + \sum_j a_j(w_{jk} + \gamma w_{jk}^+)} R_k$$

- ▶ This favors the positive contributions more than negative ones.  $(\cdot)^+$  is basically  $\max(0, \cdot)$ .
- ▶ As we increase  $\gamma$ , the negative contributions become less and less important.

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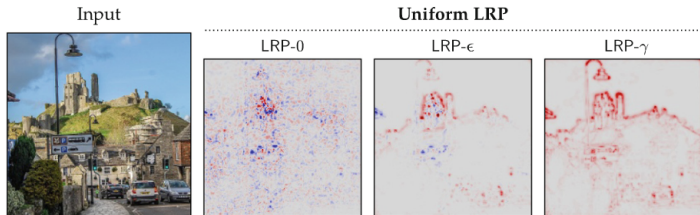
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**Figure:** Comparison of using different LRP rules uniformly across the whole network.

# Which Rule to use for each layer

- ▶ Measure of explanation quality (active research topic) \*
  - ▶ Fidelity: accurate representation of the selected output neuron
  - ▶ Understandability: Easy to interpret for a human
- Two strategies:
  - ▶ Uniform LRP
  - ▶ Composite Strategy

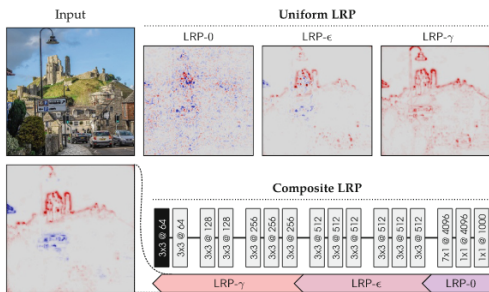


Figure: Comparing different LRP rules

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# Which Rule to use for each layer

- ▶ Uniform LRP-0
  - ▶ Tends to pick many local artifacts of the prediction functions (shattered gradient problem).

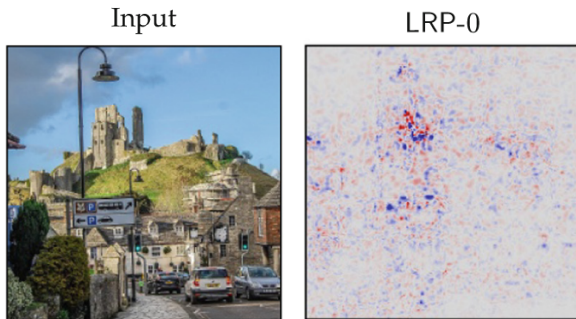


Figure: Input relevance using uniform LRP-0

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# Which Rule to use for each layer

- ▶ Uniform LRP- $\epsilon$ 
  - ▶ Faithful and accurate representation, but due to sparsity it is hard to interpret by human.

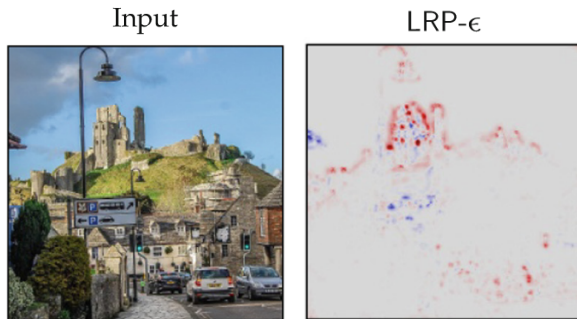


Figure: Input relevance using uniform LRP- $\epsilon$

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# Which Rule to use for each layer

- ▶ Uniform LRP- $\gamma$ 
  - ▶ It is understandable by humans because of dense highlighted features.
  - ▶ But it picks unrelated features such as lamp post.

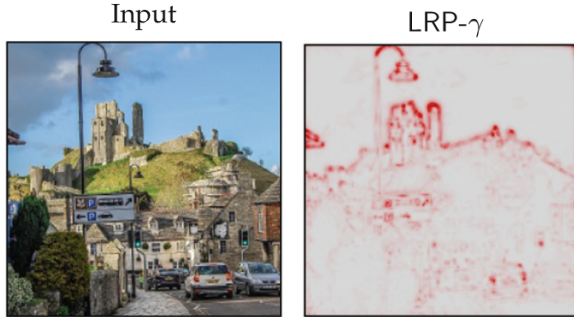


Figure: Input relevance using uniform LRP- $\gamma$

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Different starting relevance  
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## Conclusion

# Which Rule to use for each layer

- ▶ Composite LRP
  - ▶ Upper Layers (fully connected in top part): LRP-0 Concepts are entangled. Gradient is less sensitive to these entanglements. (Here we can tolerate the gradient problems because of these entanglements).
  - ▶ Middle Layers: LRP- $\epsilon$  Weight sharing in convolution introduces spurious variations which can be filtered out using this rule. Only important explanations remain.
  - ▶ Lower Layers: LRP- $\gamma$  Same problem as middle layers. Either  $\epsilon$  or  $\gamma$  should work. But later is better because it has a stronger effect in spreading the explanations to features rather than actual pixels.

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## Conclusion

# Which Rule to use for each layer

- ▶ Composite LRP
  - ▶ As you see, we have both fidelity and understandability.

Input

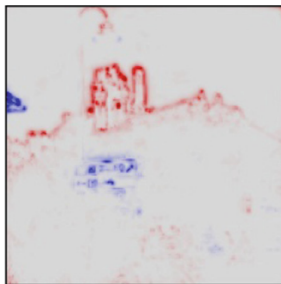


Figure: Input relevance using composite LRP

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- LRP-0
- LRP-Epsilon
- LRP-Gamma
- LRP Rules Comparison

### Which Rule to use for each layer

Different starting relevance for the output layer

## Conclusion

# Different starting relevance for the output layer \*

- ▶ What we tried to explain so far:
  - ▶ Version 1:

$$R_c = P(z_c) = \frac{e^{z_c}}{\sum_{c'} e^{z_{c'}}$$

- ▶ Version 2 (This one is more stable):

$$R_c = z_c = \sum_k a_k w_{kc}$$

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## Conclusion

# Different starting relevance for the output layer

\*\*

- ▶ Instead we can try to explain another type of score:
  - ▶ Explain the presence of an object, when other objects from other classes are present in the image. (I guess we can do this in a pairwise manner too)

$$\eta_c = \log\left(\frac{P(z_c)}{1 - P(z_c)}\right) = \log\left(\frac{P(z_c)}{\sum_{c'' \neq c} P(z_{c''})}\right)$$

$$z_{c,c''} = \log\left(\frac{P(z_c)}{P(z_{c''})}\right) = \log\left(\frac{\sum_{c'} e^{z_{c'}}}{\frac{e^{z_{c''}}}{\sum_{c'} e^{z_{c'}}}}\right) = \log\left(\frac{e^{z_c}}{e^{z_{c''}}}\right)$$

$$= \log(e^{z_c - z_{c''}}) = z_c - z_{c''} = \sum_k a_k (w_{kc} - w_{kc''})$$

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## Conclusion

# Different starting relevance for the output layer

\*\*

- ▶ Now we can use this  $z_{c,c''}$  to calculate a new Relevance for the neuron  $c$  in the output.

$$z_{c,c''} = \log\left(\frac{P(z_c)}{P(z_{c''})}\right) = \log\left(\frac{\frac{e^{z_c}}{\sum_{c'} e^{z_{c'}}}}{\frac{e^{z_{c''}}}{\sum_{c'} e^{z_{c'}}}}\right) = \log\left(\frac{e^{z_c}}{e^{z_{c''}}}\right)$$

$$= \log(e^{z_c - z_{c''}}) = z_c - z_{c''} = \sum_k a_k (w_{kc} - w_{kc''})$$

$$R_{c,c''} = z_{c,c''} \times \frac{e^{-z_{c,c''}}}{\sum_{c' \neq c} e^{-z_{c,c'}}}$$

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# Different starting relevance for the output layer

\*\*

- ▶ The new relevance:

$$R_{c,c''} = z_{c,c''} \times \frac{e^{-z_{c,c''}}}{\sum_{c' \neq c} e^{-z_{c,c'}}}$$

- ▶ This will result in better explanations.

Input



LRP explanations

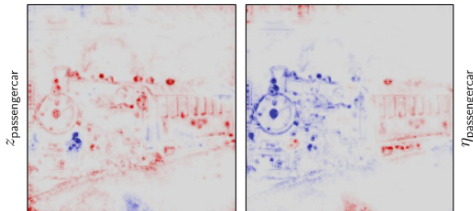


Figure: Comparing old initialized relevance for c and the new one.

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## Conclusion

# Conclusion

- ▶ There are still some vague things for myself.
  - ▶ Is manipulating rules to get better explanations OK?
  - ▶ All those \*s!
- ▶ We can illustrate the regions that the network is paying more attention (positive or negative)
- ▶ We can explain why the network is making (or not making) a particular decision
- ▶ We can use Deep Learning for sensitive tasks with a little bit more peace of mind.

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# Thank You for your attention!